

Chapter Six

Momentum Equation Dr.Abdulkareem A.Wahab

6.1 / Introduction :

In the based on the law of conservation of momentum or on the momentum principle , which states that the net force acting on a fluid mass is equal to the change in momentum of flow per unit time in the direction.

The force acting on a fluid mass (m) is given by the Newton's second law of motion :

$$\mathbf{F} = m \mathbf{a}$$

Where (a) is the acceleration acting in the same direction \mathbf{F} .

$$\text{But} \quad \mathbf{a} = \frac{dv}{dt}$$

$$\mathbf{F} = m \frac{dv}{dt} \quad (6.1)$$

$$\mathbf{F} dt = m dv \quad (6.2)$$

The equation (6.2) is known as the (impulse – momentum) equation , and states that the impulse of a force (\mathbf{F}) acting on a fluid of mass (m) in a short interval of time (dt) is equal to the change of momentum $d(mv)$ in the direction of force .

6.2 / Force exerted by a flowing fluid on a pipe bend :

The impulse – momentum equation (6.2) is used to determine the resultant force exerted by a flowing fluid on a pipe bend .

Consider two sections (1) & (2) , as shown in Fig.(6.1)

V_1 , P_1 , A_1 are velocity , pressure and area at section (1)

V_2 , P_2 , A_2 are velocity , pressure and area at section (2) .

Let F_x , F_y be the components of force exerted by the flowing fluid on the bend in x – direction and y – direction respectively .

The other external forces acting on the fluid are $p_1 A_1$ and $p_2 A_2$ on the sections (1) and (2) respectively. Then momentum equation in x – direction is given by:

$$\sum F_x = \dot{m} \Delta v_x \quad (6.3)$$

And in y – direction $\sum F_y = \dot{m} \Delta v_y$ (6.4)

There are two cases for the bend , first case when the angle of bend is $\theta \leq 90^\circ$ and the second case , when the angle of bend is $90^\circ \leq \theta \leq 180^\circ$.

First case ($\theta \leq 90^\circ$) :

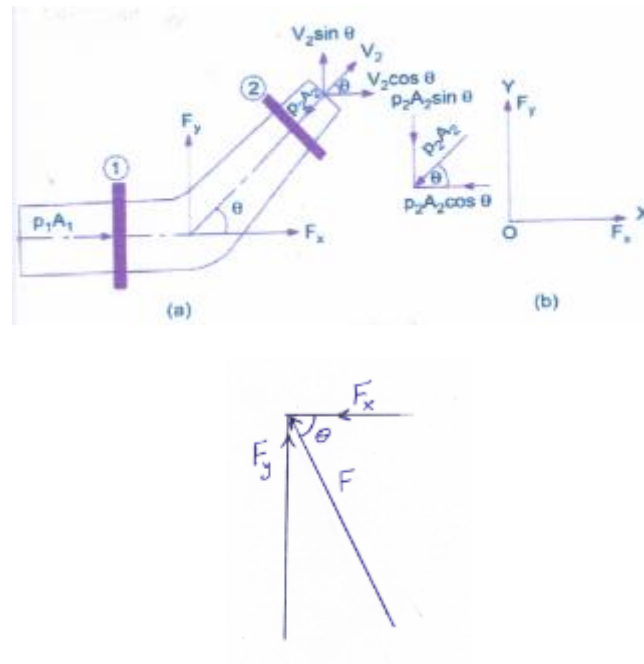


Fig.(6.1) Forces on bend

Applying eq.(6.3) , in x – direction :

$$p_1 A_1 - p_2 A_2 \cos \theta - F_x = \rho Q (V_2 \cos \theta - V_1)$$

$$F_x = - \rho Q (V_2 \cos \theta - V_1) + p_1 A_1 - p_2 A_2 \cos \theta$$

$$F_x = \rho Q (V_1 - V_2 \cos \theta) + p_1 A_1 - p_2 A_2 \cos \theta \quad (6.5)$$

Similarly the momentum equation (6.4) in y – direction gives (the weight of bend is acting in y – direction only , and neglected) :

$$F_y - p_2 A_2 \sin \theta = \rho Q (v_2 \sin \theta - 0)$$

$$F_y = \rho Q v_2 \sin \theta + p_2 A_2 \sin \theta \quad (6.6)$$

The resultant force (F_R) acting on the bend :

$$F_R = \sqrt{F_x^2 + F_y^2} \quad (6.7)$$

And the angle made by the resultant force (F_R) with horizontal direction is given by :

$$\tan\theta = \frac{F_y}{F_x} \quad (6.8)$$

Second case ($180^\circ \geq \theta \geq 90^\circ$:

When the angle θ (angle of bend) with horizontal direction less than 180° and more than 90° , as shown in Fig. (6.2).

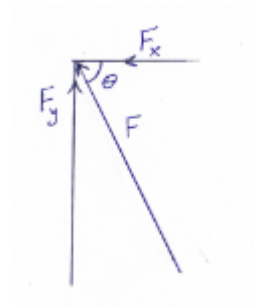
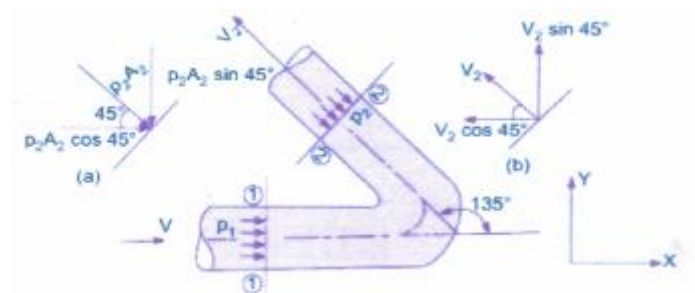


Fig.(6.2)

Applying eq.(6.3) in x – direction :

$$\sum F_x = \dot{m} \Delta v_x \quad (6.3)$$

$$p_1 A_1 + p_2 A_2 \cos\theta - F_x = \rho Q (V_2 \cos\theta - V_1)$$

$$F_x = p_1 A_1 + p_2 A_2 \cos\theta - \rho Q (V_2 \cos\theta - V_1) \quad (6.9)$$

Applying eq.(6.4) in y – direction :

$$\sum F_y = \dot{m} \Delta v_y \quad (6.4)$$

$$F_y - p_2 A_2 \sin\theta = \rho Q (V_2 \sin\theta - 0)$$

$$F_y = \rho Q (V_2 \sin\theta) + p_2 A_2 \sin\theta \quad (6.10)$$

The resultant of forces (F_R) :

$$F_R = \sqrt{F_x^2 + F_y^2} \quad (6.11)$$

$$\tan \theta = \frac{F_y}{F_x} (6.12)$$