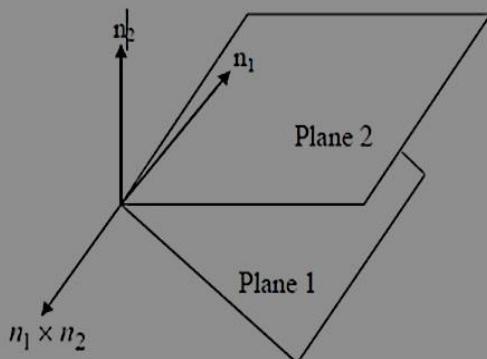


3.3 Vectors analysis/angle between two planes

Angle between planes

The angle between two intersecting planes is defined to be the acute angle between their normal vectors.

$$\theta = \cos^{-1} \left(\frac{\mathbf{n}_1 \cdot \mathbf{n}_2}{|\mathbf{n}_1| |\mathbf{n}_2|} \right)$$



Example: Find the angle between the planes $2x - 6y - z = 5$ and $x + 2y - 2z = 12$

Solution//

$$\mathbf{n}_1 = 2\mathbf{i} - 6\mathbf{j} - \mathbf{k}$$

$$\mathbf{n}_2 = \mathbf{i} + 2\mathbf{j} - 2\mathbf{k}$$

$$|\mathbf{n}_1| = \sqrt{4 + 36 + 1} = \sqrt{41}$$

$$|n2| = \sqrt{1+4+4} = \sqrt{9}$$

$$\theta = \cos^{-1} \frac{\mathbf{n1} \cdot \mathbf{n2}}{|\mathbf{n1}| \cdot |\mathbf{n2}|} = \cos^{-1} \frac{-8}{\sqrt{41} \cdot \sqrt{9}} = 114.6^\circ$$

3.4 Vectors analysis/intersection line & plane

Example: Find the vector parallel to the line of intersection of the planes $3x-6y-2z=15$, $x+2y-z=5$.

Solution/

$$\mathbf{N1} = 3\mathbf{i} - 6\mathbf{j} - 2\mathbf{k}$$

$$\mathbf{N2} = \mathbf{i} + 2\mathbf{j} - \mathbf{k}$$

$$\mathbf{N} = \mathbf{N1} \times \mathbf{N2} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 3 & -6 & -2 \\ 1 & 2 & -1 \end{vmatrix}$$

$$= 10 \mathbf{i} + \mathbf{j} + 12\mathbf{k}$$

3.5 Vector Functions

A vector –valued function of real variable can be written in component form as:

$$\mathbf{F}(t) = F_1(t)\mathbf{i} + F_2(t)\mathbf{j} + F_3(t)\mathbf{k}$$

1. Limits

If $\mathbf{L} = L_1\mathbf{i} + L_2\mathbf{j} + L_3\mathbf{k}$ is a vector in space

$\mathbf{F}(t)$ is a vector function

$$\mathbf{F}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$$

$$\lim_{t \rightarrow a} f(t) = \lim_{t \rightarrow a} f_1(t) + \lim_{t \rightarrow a} f_2(t) + \lim_{t \rightarrow a} f_3(t)$$

Example: Find $\lim_{t \rightarrow \pi} f(t)$ If $f(t) = \cos t \mathbf{i} + 3 \sin t \mathbf{j} + t^3 \mathbf{k}$

Solution//

$$\begin{aligned}\lim_{t \rightarrow \pi} f(t) &= \lim_{t \rightarrow \pi} (\cos t \mathbf{i} + 3 \sin t \mathbf{j} + t^3 \mathbf{k}) \\ &= \lim_{t \rightarrow \pi} \cos t \mathbf{i} + \lim_{t \rightarrow \pi} 3 \sin t \mathbf{j} + \lim_{t \rightarrow \pi} t^3 \mathbf{k} = -\mathbf{i} + 0\mathbf{j} + \pi^3 \mathbf{k}\end{aligned}$$

2.Derivative

$$\mathbf{r}(t) = \mathbf{f}(t)\mathbf{i} + \mathbf{g}(t)\mathbf{j} + \mathbf{h}(t)\mathbf{k}$$

$$\Delta \mathbf{r} = \mathbf{r}(t + \Delta t) - \mathbf{r}(t) \dots \dots \dots 1$$

Then if $\mathbf{r}(t)$ sub in equation 1

$$\begin{aligned}\Delta \mathbf{r} &= \{\mathbf{f}(t + \Delta t) - \mathbf{f}(t)\}\mathbf{i} + \{\mathbf{g}(t + \Delta t) - \mathbf{g}(t)\}\mathbf{j} \\ &\quad + \{\mathbf{h}(t + \Delta t) - \mathbf{h}(t)\}\mathbf{k}\end{aligned}$$

As $\Delta t = 0$

$$\begin{aligned}\frac{d\mathbf{r}}{dt} &= \lim_{\Delta t \rightarrow 0} \frac{\Delta \mathbf{r}}{\Delta t} \\ &= \lim_{\Delta t \rightarrow 0} \frac{\{\mathbf{g}(t + \Delta t) - \mathbf{g}(t)\}\mathbf{j}}{\Delta t} + \lim_{\Delta t \rightarrow 0} \frac{\{\mathbf{h}(t + \Delta t) - \mathbf{h}(t)\}\mathbf{k}}{\Delta t} + \lim_{\Delta t \rightarrow 0} \frac{\{\mathbf{f}(t + \Delta t) - \mathbf{f}(t)\}\mathbf{i}}{\Delta t} \\ \frac{d\mathbf{r}}{dt} &= \frac{df}{dt} \mathbf{i} + \frac{dg}{dt} \mathbf{j} + \frac{dr}{dt} \mathbf{k}\end{aligned}$$

Notes//

1. Velocity $= \frac{dr}{dt} = \bar{V}$

2. Acceleration $a = \frac{d^2r}{dt^2} = \frac{dv}{dt}$

3. Speed or magnitude of velocity $= |V|$

Or velocity $\bar{V} = \text{speed}|V| * \text{direction}$

Example: Find speed and direction of $r(t)$ when $t=2$ If $r(t) = t^2\mathbf{i} + 2t^2\mathbf{j} + 5\mathbf{k}$

Solution//

$$\frac{dr}{dt} = \bar{V} = 3t^2\mathbf{i} + 4t\mathbf{j} + 0\mathbf{k}$$

$$\text{speed} = |V| = \sqrt{(3t^2)^2 + (4t)^2}$$

$$\text{At } t=2 \rightarrow |V| = 14.4$$

$$\text{Direction (at } t=2) = \frac{\bar{v}}{|V|}$$

$$= \frac{12\mathbf{i} + 8\mathbf{j} + 0\mathbf{k}}{14.4}$$

Differential rules

1. $\frac{dc}{dt} = 0$ if $c = \text{constant}$

Example : $c = 2\mathbf{i} + 4\mathbf{j} + 5\mathbf{k}$, $\frac{dc}{dt} = 0\mathbf{i} + 0\mathbf{j} + 0\mathbf{k} = \mathbf{0}$

2. if $u(t)$ is a vector function, then $\frac{d cu}{dt} = c \cdot \frac{du}{dt}$

where c is constant a vector

3. $\frac{d(u \pm v)}{dt} = \frac{du}{dt} \pm \frac{dv}{dt}$ (**u&v are vector function**)

4. $\frac{d(u.v)}{dt} = u \cdot \frac{dv}{dt} + v \cdot \frac{du}{dt}$ (**u&v are vector function**)

5. $\frac{d(uxv)}{dt} = u \ x \frac{dv}{dt} + v \ x \frac{du}{dt}$ (**u&v are vector function**)

Chain rule

If $r(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$ is a function of S then

$$\frac{dr}{ds} = \frac{dr}{dt} \cdot \frac{dt}{ds}$$

Note: $u(t)$ is a function vector has constant length then

$$\bar{u} \cdot \overline{\frac{du}{dt}} = 0 \text{ or } \bar{u} \perp \overline{\frac{du}{dt}}$$

Example: show that $u(t) = \sin t \mathbf{i} + \cos t \mathbf{j} + 5\mathbf{k}$ has constant length and is orthogonal to its derivative

Solution//

$$\bar{u} \cdot \overline{\frac{du}{dt}} = 0$$

$$u(t) = \sin t \mathbf{i} + \cos t \mathbf{j} + 5\mathbf{k}$$

$$\frac{du}{dt} = \cos t \mathbf{i} - \sin t \mathbf{j} + 0\mathbf{k}$$

$$\bar{u} \cdot \overline{\frac{du}{dt}} = \sin t \cos t - \sin t \cos t + 0 = 0$$