

# Al-Mustaqbal University Department Biomedical engineering Class second Subject Math. ecturer (Dr.alaa mohammed Hussein wa

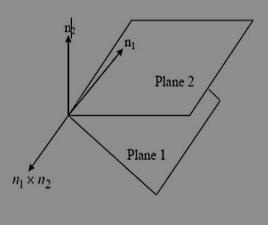
(Lecturer (Dr.alaa mohammed Hussein wais) 1<sup>st</sup> term – Lect. (Vector)

### 3.3 Vectors analysis/angle between two planes

### Angle between planes

The angle between two intersecting planes is defined to be the acute angle between their normal vectors.

$$\theta = \cos^{-1} \left( \frac{n_1 \cdot n_2}{|n_1| |n_2|} \right)$$



Example: Find the angle between the planes 2x - 6y - z = 5 and x + 2y - 2z = 12

Solution//

$$n_1=2i-6j-k$$

$$n2=i+2j-2k$$



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$$|n1| = \sqrt{4 + 36 + 1} = \sqrt{41}$$

$$|n2| = \sqrt{1 + 4 + 4} = \sqrt{9}$$

$$\theta = \cos^{-1} \frac{n1 \cdot n2}{|n1| \cdot |n2|} = \cos^{-1} \frac{-8}{\sqrt{41} \sqrt{9}} = 114 \cdot 6^{\circ}$$

### 3.4 Vectors analysis/intersection line &plane

Example: Find the vector parallel to the line of intersection of the planes 3x-6y-2z=15, x+2y-z=5.

Solution/

$$N2=i+2j-k$$

$$N=N1 \times N2 = \begin{vmatrix} i & j & k \\ 3 & -6 & -2 \\ 1 & 2 & -1 \end{vmatrix}$$

$$=10 i+j+12k$$

### 3.5 Vector Functions

A vector –valued function of real variable can be written in component form as:

$$F(t)=F1(t)i+F2(t)j+F3(t)k$$

### 1. Limits

If L=L1i+L2j+L3k is a vector in space



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### **F**(t) is a vector function

$$F(t)=f(t)i+g(t)j+h(t)k$$

$$\lim_{t\to a} f(t) = \lim_{t\to a} f(t) + \lim_{t\to a} f(t) + \lim_{t\to a} f(t)$$

Example: Find 
$$\lim_{t\to\pi} f(t)$$
 If  $f(t) = \cos t \, i + 3 \sin t \, j + t^3 k$ 

Solution//

$$\lim_{t\to\pi}f(t)=\lim_{t\to\pi}(\cos t\;i+3\sin t\;j+t^3k$$

$$=\lim_{t\to\pi}\cos t\ i+\lim_{t\to\pi}3\sin t\ j+\lim_{t\to\pi}t^3k=-1i+0j+\pi^3k$$

#### 2.Derivative

$$r(t)=f(t)i+g(t)j+h(t)k$$

$$\Delta r = r(t + \Delta t) - r(t) \dots \dots \dots 1$$

Then if r(t) sub in equation 1

$$\Delta r = \{f(t + \Delta t) - f(t)\}i + \{g(t + \Delta t) - g(t)\}j$$
$$+ \{h(t + \Delta t) - h(t)\}k$$

 $\mathbf{As} \, \Delta t = \mathbf{0}$ 

$$\frac{dr}{dt} = \lim_{\Delta t \to 0} \frac{\Delta r}{\Delta t}$$

$$= \lim_{\Delta t \to 0} \frac{\{g(t + \Delta t) - g(t)\}j}{\Delta t} + \lim_{\Delta t \to 0} \frac{\{h(t + \Delta t) - h(t)\}k}{\Delta t} + \lim_{\Delta t \to 0} \frac{\{f(t + \Delta t) - f(t)\}i}{\Delta t}$$



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$$\frac{dr}{dt} = \frac{df}{dt}i + \frac{dg}{dt}j + \frac{dr}{dt}k$$

Notes//

1. Velocity=
$$\frac{dr}{dt} = \overline{V}$$

2. Acceleration 
$$a = \frac{d^2r}{dt^2} = \frac{dv}{dt}$$

3. Speed or magnitude of velocity =|V|

Or velocity 
$$\overline{V} = speed |V| * direction$$

Example: Find speed and direction of r(t) when t=2 If  $r(t) = t^2i + 2t^2j + 5k$ 

Solution//

$$\frac{dr}{dt} = \overline{V} = 3t^2i + 4tj + 0k$$

speed =
$$|V| = \sqrt{(3t^2)^2 + (4t)^2}$$

At 
$$t=2 \rightarrow |V| = 14.4$$

Direction (at t=2) = 
$$\frac{\overline{v}}{|V|}$$
  
=  $\frac{12 i + 8 j + 0 k}{14.4}$ 



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### **Differential rules**

$$1.\frac{dc}{dt} = 0 if c = constant$$

Example :c=2i+4j+5k, 
$$\frac{dc}{dt} = 0i + 0j + 0k = 0$$

2. if 
$$u(t)$$
 is a vector function, then  $\frac{dcu}{dt} = c \cdot \frac{du}{dt}$ 

where c is constant a vector

$$3.\frac{d(u\pm v)}{dt} = \frac{du}{dt} \pm \frac{dv}{dt} (u\&v \ are \ vector \ function)$$

$$4.\frac{d(u.v)}{dt} = u.\frac{dv}{dt} + v.\frac{du}{dt}(u\&v \ are \ vector \ function)$$

$$5.\frac{d(uxv)}{dt} = u x \frac{dv}{dt} + v x \frac{du}{dt} (u \& v \text{ are vector function})$$

#### Chain rule

If r(t)=f(t)i+g(t)j+h(t)k is a function of S then

$$\frac{dr}{ds} = \frac{dr}{dt} \cdot \frac{dt}{ds}$$

**Note:** u(t) is a function vector has constant length then

$$\overline{u}.\frac{\overline{du}}{dt} = 0 \text{ or } \overline{u}^{\perp}\frac{\overline{du}}{dt}$$

Example: show that  $u(t)=\sin t i + \cos t j +$ 

5k has constant length and is orthogonal to its derivative

Solution//



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$$\overline{u}.\frac{\overline{du}}{dt}=0$$

$$\mathbf{u}(t) = \sin t \, \mathbf{i} + \cos t \, \mathbf{j} + 5\mathbf{k}$$

$$\frac{du}{dt} = \cos t \, i\text{-}\sin t \, j + 0k$$

$$\overline{u}.\frac{\overline{du}}{dt} = sin \ t \ cos \ t - sin \ t \ cos \ t + 0 = 0$$