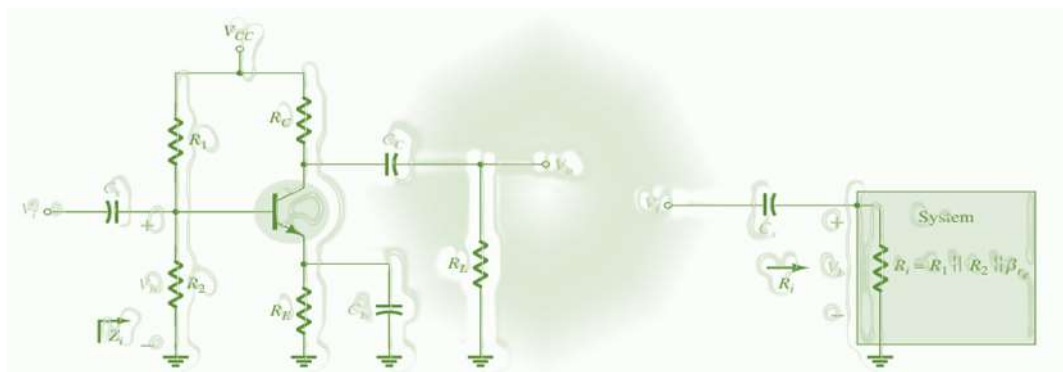




## Electronic Circuit

### Lecture 3 (4<sup>th</sup> & 5<sup>th</sup> Week)

## BJT & FET Frequency Response





### 1.1. Introduction to BJT Amplifiers

The frequency response of a Bipolar Junction Transistor (BJT) describes how its performance changes with varying signal frequency. The response varies across low, and high frequencies.

- ✚ **Low Frequencies:** The performance is affected by coupling and bypass capacitors, leading to a drop in response at very low frequencies.
- ✚ **High Frequencies:** The effects of parasitic capacitances (such as base-collector capacitance  $C_{bc}$  and base-emitter capacitance  $C_{be}$  become significant, reducing gain and altering circuit response.

### 1.2 Low Frequency Response BJT Amplifier with $R_L$

The analysis of this section will employ the loaded  $R_L$  voltage-divider BJT bias configuration introduced earlier lecture. For the network of Fig. 1, the capacitors  $C_s$ ,  $C_c$ , and  $C_E$  will determine the low-frequency response. We will now examine the impact of each independently in the order listed.

$C_s$  Because is normally connected between the applied source and the active device, the general form of the  $RC$  configuration is established by the network of Fig. 2, matching that with  $R_i = R_1 \parallel R_2 \parallel \beta r_e$ .

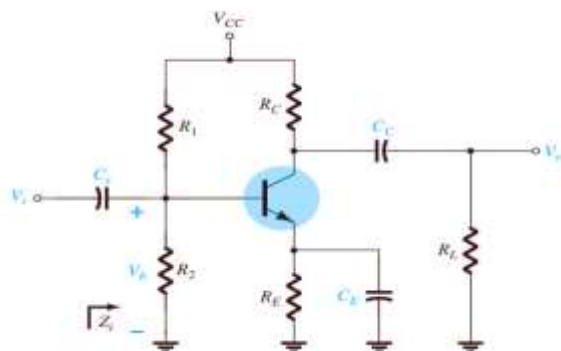


Fig.1. Loaded BJT amplifier with capacitors that affect the low- frequency response.

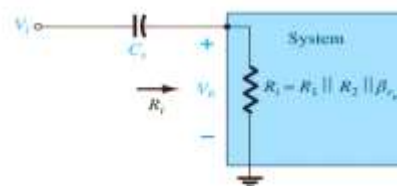


Fig.2. Determining the effect of  $C_s$  on the low-frequency response.



Applying the voltage-divider rule:

$$V_b = \frac{R_i V_i}{R_i - jX_{C_s}}$$

The cutoff frequency defined by  $C_s$  can be determined by manipulating the above equation into a standard form or simply. For future RC networks, will simply be applied.

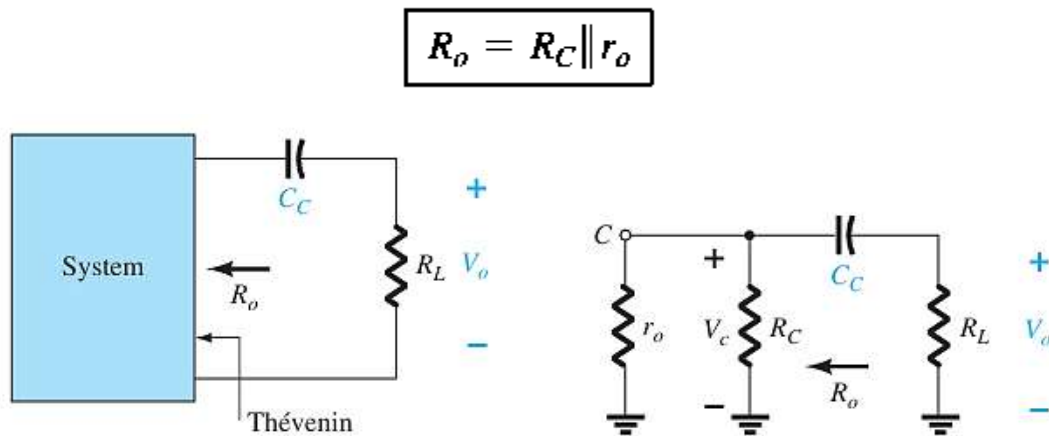
$$f_{L_s} = \frac{1}{2\pi R_i C_s}$$

For the network of Fig.1, when we analyze the effects of  $C_s$  we must make the assumption that  $C_E$  and  $C_c$  are performing their designed function or the analysis becomes too unwieldy, that is, that the magnitudes of the reactance of  $C_E$  and  $C_c$  permit employing a short-circuit equivalent in comparison to the magnitude of the other series impedances.

**$C_c$**  Because the coupling capacitor is normally connected between the output of the active device and the applied load, the RC configuration that determines the low-cutoff frequency due to  $C_c$  appears in Fig.3. The total series resistance is now  $R_o + R_L$ , and the cutoff frequency due to  $C_c$  is determined by:

$$f_{L_c} = \frac{1}{2\pi(R_o + R_L)C_c}$$

Ignoring the effects of  $C_s$  and  $C_E$ , we find that the output voltage  $V_o$ . For the network of Fig.3, the ac equivalent network for the output section with  $V_i = 0$  V appears in Fig.3 The resulting value for  $R_o$  in Eq. below is then simply:



**Fig.3. Determining the effect of  $C_c$  on the low-frequency response. Localized ac equivalent for  $C_c$  with  $V_i=0$  V.**

CE To determine  $f_{LE}$ , the network “seen” by CE must be determined as shown in Fig.4. Once the level of  $R_e$  is established, the cutoff frequency due to CE can be determined using the following equation:

$$f_{LE} = \frac{1}{2\pi R_e C_E}$$

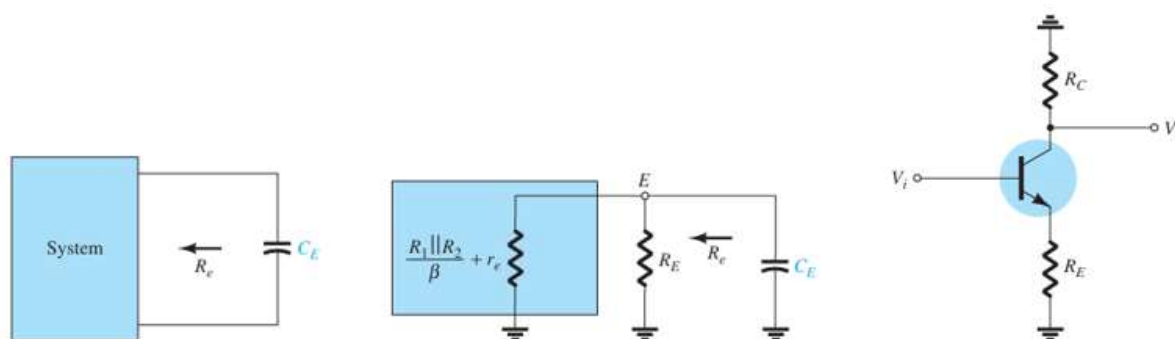
For the network, the ac equivalent as “seen” by CE appears in Fig.4. The value of  $R_e$  is therefore determined by:

$$R_e = R_E \parallel \left( \frac{R_1 \parallel R_2}{\beta} + r_e \right)$$

The effect of CE on the gain is best described in a quantitative manner by recalling that the gain for the configuration of Fig.4. is given by



$$A_v = \frac{-R_C}{r_e + R_E}$$



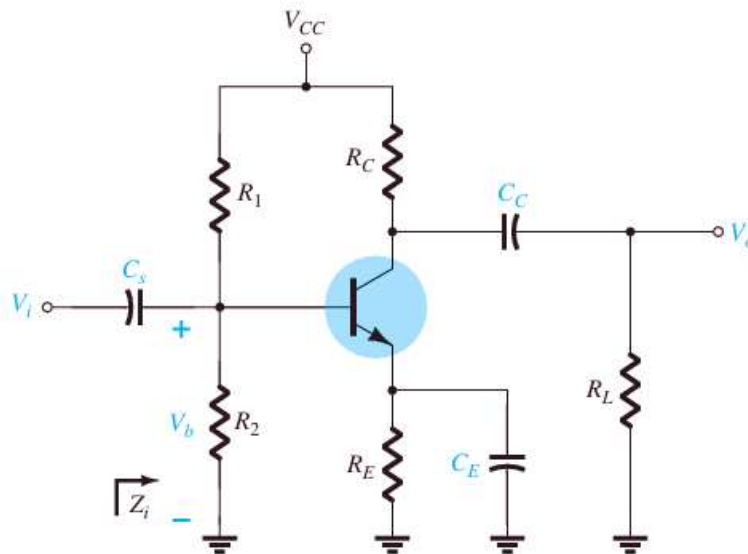
**Fig.4. (a)Determining the effect of CE on the low-frequency response. (b) Localized ac equivalent of CE. (c) Network employed to describe the effect of CE on the amplifier gain.**

The maximum gain is obviously available where  $R_E$  is 0. At low frequencies, with the bypass capacitor  $C_E$  in its “open-circuit” equivalent state, all of  $R_E$  appears in the gain equation above, resulting in the minimum gain. As the frequency increases, the reactance of the capacitor  $C_E$  will decrease, reducing the parallel impedance of  $R_E$  and  $C_E$  until the resistor  $R_E$  is effectively “shorted out” by  $C_E$ . The result is a maximum or midband gain determined by  $A_v = -R_C/r_e$ . At  $f_{LE}$  the gain will be 3 dB below the midband value determined with  $R_E$  “shorted out.”



**Example1:** Determine the cutoff frequencies for the network of Fig.1. using the following parameters:

$C_s = 10 \text{ mF}$ ,  $C_E = 20 \text{ mF}$ ,  $C_C = 1 \text{ mF}$   
 $R_1 = 40 \text{ k}\Omega$ ,  $R_2 = 10 \text{ k}\Omega$ ,  $R_E = 2 \text{ k}\Omega$ ,  
 $R_C = 4 \text{ k}\Omega$ ,  $R_L = 2.2 \text{ k}\Omega$ ,  $\beta = 100$ ,  $V_{CC} = 20 \text{ V}$



**Sol:**

To determine  $r_e$  for dc conditions, we first apply the test equation:

$$\beta R_E = (100)(2 \text{ k}\Omega) = 200 \text{ k}\Omega \gg 10R_2 = 100 \text{ k}\Omega$$

Since satisfied the dc base voltage is determined by

$$V_B \cong \frac{R_2 V_{CC}}{R_2 + R_1} = \frac{10 \text{ k}\Omega (20 \text{ V})}{10 \text{ k}\Omega + 40 \text{ k}\Omega} = \frac{200 \text{ V}}{50} = 4 \text{ V}$$

with

$$I_E = \frac{V_E}{R_E} = \frac{4 \text{ V} - 0.7 \text{ V}}{2 \text{ k}\Omega} = \frac{3.3 \text{ V}}{2 \text{ k}\Omega} = 1.65 \text{ mA}$$

so that

$$r_e = \frac{26 \text{ mV}}{1.65 \text{ mA}} \cong \mathbf{15.76 \text{ }\Omega}$$

and

$$\beta r_e = 100(15.76 \text{ }\Omega) = 1576 \text{ }\Omega = \mathbf{1.576 \text{ k}\Omega}$$



**Midband Gain**  $A_v = \frac{V_o}{V_i} = \frac{-R_C \parallel R_L}{r_e} = -\frac{(4 \text{ k}\Omega) \parallel (2.2 \text{ k}\Omega)}{15.76 \Omega} \cong -90$

**C<sub>s</sub>**  $R_i = R_1 \parallel R_2 \parallel \beta r_e = 40 \text{ k}\Omega \parallel 10 \text{ k}\Omega \parallel 1.576 \text{ k}\Omega \cong 1.32 \text{ k}\Omega$

$$f_{L_s} = \frac{1}{2\pi R_i C_s} = \frac{1}{(6.28)(1.32 \text{ k}\Omega)(10 \mu\text{F})}$$

$$f_{L_s} \cong \mathbf{12.06 \text{ Hz}}$$

**C<sub>c</sub>**  $f_{L_c} = \frac{1}{2\pi(R_o + R_L)C_C} \quad \text{with} \quad R_o = R_C \parallel r_o \cong R_C$

$$= \frac{1}{(6.28)(4 \text{ k}\Omega + 2.2 \text{ k}\Omega)(1 \mu\text{F})}$$

$$\cong \mathbf{25.68 \text{ Hz}}$$

**C<sub>E</sub>**  $R_e = R_E \parallel \left( \frac{R_1 \parallel R_2}{\beta} + r_e \right)$

$$= 2 \text{ k}\Omega \parallel \left( \frac{40 \text{ k}\Omega \parallel 10 \text{ k}\Omega}{100} + 15.76 \Omega \right)$$

$$= 2 \text{ k}\Omega \parallel \left( \frac{8 \text{ k}\Omega}{100} + 15.76 \Omega \right)$$

$$= 2 \text{ k}\Omega \parallel (80 \Omega + 15.76 \Omega)$$

$$= 2 \text{ k}\Omega \parallel 95.76 \Omega$$

$$= 91.38 \Omega$$

$$f_{L_E} = \frac{1}{2\pi R_e C_E} = \frac{1}{(6.28)(91.38 \Omega)(20 \mu\text{F})} = \frac{10^6}{11,477.73} \cong \mathbf{87.13 \text{ Hz}}$$

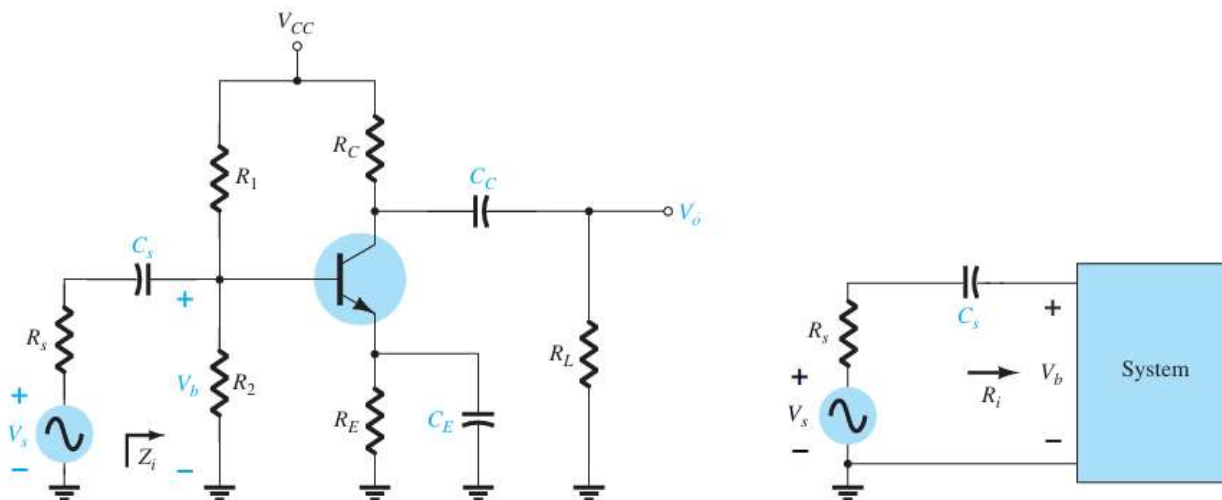
Since  $f_{L_E} \gg f_{L_C}$  or  $f_{L_s}$  the bypass capacitor  $C_E$  is determining the lower cutoff frequency of the amplifier.



### 1.3 Impact of $R_s$ on the BJT Low Frequency response

In this section we will investigate the impact of the source resistance on the various cutoff frequencies. In Fig. 5 a signal source and associated resistance have been added to the configuration of Fig.1. The gain will now be between the output voltage  $V_o$  and the signal source  $V_s$ .

As The equivalent circuit at the input is now as shown in Fig.5, with  $R_i$  continuing to be equal to  $R_1 \parallel R_2 \parallel \beta r_e$ .



**Fig.5. Determining the effect of  $R_s$  on the low-frequency response of a BJT amplifier. Determining the effect of  $C_s$  on the low frequency response.**

Using the results of the last section it would appear we could simply find the total sum of the series resistors. Doing so would result in the following equation for the cutoff frequency:

$$f_{L_s} = \frac{1}{2\pi(R_i + R_s)C_s}$$





However, it would be best to validate our assumption by first applying the voltage-divider rule in the following manner:

$$V_b = \frac{R_i V_s}{R_s + R_i - jX_{C_s}}$$

For the midband frequencies, the input network will appear as shown:

$$A_{v_{mid}} = \frac{V_b}{V_s} = \frac{R_i}{R_i + R_s}$$

Noting the similarities with Eq. above the cutoff frequency is defined by  $f_{L_s}$  above and:

$$f_{L_s} = \frac{1}{2\pi(R_s + R_i)C_s}$$

Cc Reviewing the analysis for the coupling capacitor Cc, we find that the derivation of the equation for the cutoff frequency remains the same. That is,

$$f_{L_C} = \frac{1}{2\pi(R_o + R_L)C_C}$$

CE Again, following the analysis for the same capacitor, we find that Rs will affect the resistance level substituted into the cutoff equation so that

$$f_{L_E} = \frac{1}{2\pi R_e C_E}$$



**Example 2:** Repeat the analysis of Example 1 but with a source resistance  $R_s$  of  $1\text{ k}\Omega$ . The gain of interest will now be  $V_o/V_s$  rather than  $V_o/V_i$ . Compare results.

**Sol/** The dc conditions remain the same:

$$r_e = 15.76\ \Omega \text{ and } \beta r_e = 1.576\text{ k}\Omega$$

**Midband Gain**  $A_v = \frac{V_o}{V_i} = \frac{-R_C \parallel R_L}{r_e} \cong -90 \text{ as before}$

The input impedance is given by

$$\begin{aligned} Z_i = R_i &= R_1 \parallel R_2 \parallel \beta r_e \\ &= 40\text{ k}\Omega \parallel 10\text{ k}\Omega \parallel 1.576\text{ k}\Omega \\ &\cong 1.32\text{ k}\Omega \end{aligned}$$

and from Fig. 9.35,

$$V_b = \frac{R_i V_s}{R_i + R_s}$$

or  $\frac{V_b}{V_s} = \frac{R_i}{R_i + R_s} = \frac{1.32\text{ k}\Omega}{1.32\text{ k}\Omega + 1\text{ k}\Omega} = 0.569$

so that  $A_{v_s} = \frac{V_o}{V_s} = \frac{V_o}{V_i} \cdot \frac{V_b}{V_s} = (-90)(0.569)$   
 $= -51.21$

**$C_s$**   $R_i = R_1 \parallel R_2 \parallel \beta r_e = 40\text{ k}\Omega \parallel 10\text{ k}\Omega \parallel 1.576\text{ k}\Omega \cong 1.32\text{ k}\Omega$

$$f_{L_s} = \frac{1}{2\pi(R_s + R_i)C_s} = \frac{1}{(6.28)(1\text{ k}\Omega + 1.32\text{ k}\Omega)(10\ \mu\text{F})}$$

$$f_{L_s} \cong 6.86\text{ Hz vs. } 12.06\text{ Hz without } R_s$$

**$C_C$**   $f_{L_C} = \frac{1}{2\pi(R_C + R_L)C_C}$   
 $= \frac{1}{(6.28)(4\text{ k}\Omega + 2.2\text{ k}\Omega)(1\ \mu\text{F})}$   
 $\cong 25.68\text{ Hz as before}$

**$C_E$**   $R'_s = R_s \parallel R_1 \parallel R_2 = 1\text{ k}\Omega \parallel 40\text{ k}\Omega \parallel 10\text{ k}\Omega \cong 0.889\text{ k}\Omega$   
 $R_e = R_E \parallel \left( \frac{R'_s}{\beta} + r_e \right) = 2\text{ k}\Omega \parallel \left( \frac{0.889\text{ k}\Omega}{100} + 15.76\ \Omega \right)$   
 $= 2\text{ k}\Omega \parallel (8.89\ \Omega + 15.76\ \Omega) = 2\text{ k}\Omega \parallel 24.65\ \Omega \cong 24.35\ \Omega$   
 $f_{L_E} = \frac{1}{2\pi R_e C_E} = \frac{1}{(6.28)(24.35\ \Omega)(20\ \mu\text{F})} = \frac{10^6}{3058.36}$   
 $\cong 327\text{ Hz vs. } 87.13\text{ Hz without } R_s$



#### 1.4. High Frequency response BJT Amplifier

At the high-frequency end, there are two factors that define the -3-dB cutoff point: the network capacitance (parasitic and introduced) and the frequency dependence of  $h_{fe} (\beta)$ .

In the high-frequency region, the RC network of concern has the configuration appearing in Fig.6. At increasing frequencies, the reactance  $X_C$  will decrease in magnitude, resulting in a shorting effect across the output and a decrease in gain. The derivation leading to the corner frequency for this RC configuration follows along similar lines to that encountered for the low-frequency region. The most significant difference is in the following general form of  $A_v$ :

$$A_v = \frac{1}{1 + j(f/f_H)}$$

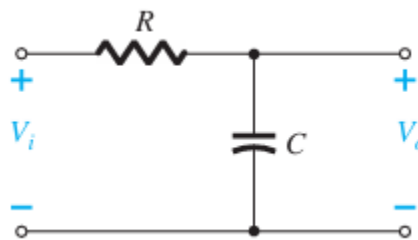


Fig.6. RC combination that will define a high-cutoff frequency.



In Fig. 8, the various parasitic capacitances ( $C_{be}$ ,  $C_{bc}$ ,  $C_{ce}$ ) of the transistor are included with the wiring capacitances ( $C_{Wi}$ ,  $C_{Wo}$ ) introduced during construction.

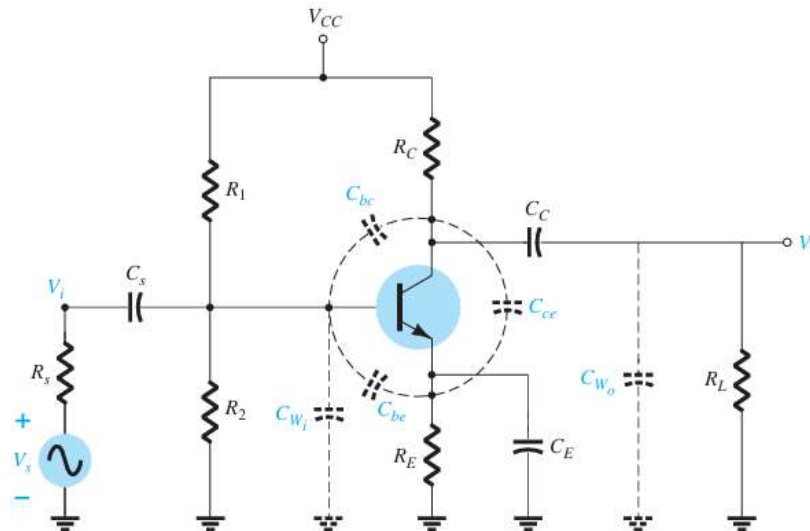


Fig.8. the capacitors that affect the high-frequency response.

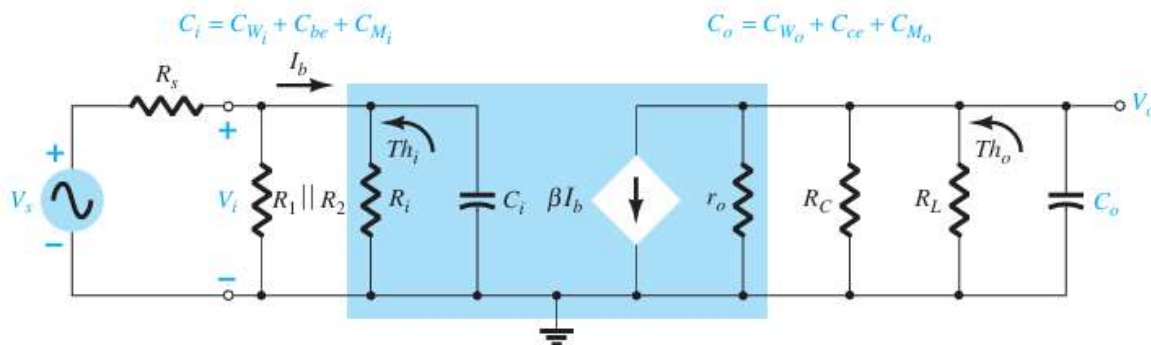


Fig.9. High-frequency ac equivalent model for the network of Fig.8



Determining the Thevenin equivalent circuit for the input and output networks of Fig.8 results in the configurations of Fig.9. For the input network, the 3-dB frequency is defined by:

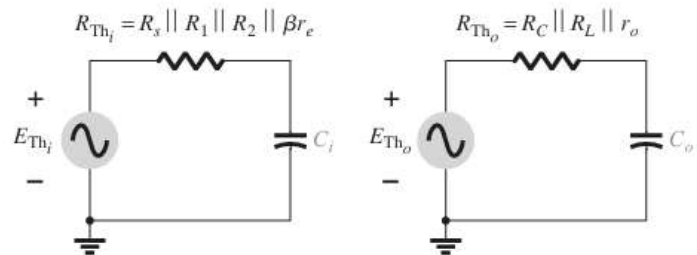
$$f_{H_i} = \frac{1}{2\pi R_{Th_i} C_i}$$

with

$$R_{Th_i} = R_s \parallel R_1 \parallel R_2 \parallel \beta r_e$$

and

$$C_i = C_{W_i} + C_{be} + C_{M_i} = C_{W_i} + C_{be} + (1 - A_v)C_{bc}$$



At very high frequencies, the effect of  $C_i$  is to reduce the total impedance of the parallel combination of  $R_1$ ,  $R_2$ ,  $\beta r_e$ , and  $C_i$  in Fig.9. The result is a reduced level of voltage across  $C_i$ , a reduction in  $I_b$ , and a gain for the system. For the output network,

$$f_{H_o} = \frac{1}{2\pi R_{Th_o} C_o}$$

with

$$R_{Th_o} = R_C \parallel R_L \parallel r_o$$

and

$$C_o = C_{W_o} + C_{ce} + C_{M_o}$$

or

$$C_o = C_{W_o} + C_{ce} + (1 - 1/A_v)C_{bc}$$

For  $A_v$  large (typical):

$$1 \gg 1/A_v$$

and

$$C_o \cong C_{W_o} + C_{ce} + C_{bc}$$



**Example 3:** Use the network of Fig.1. with the same parameters as in

Example.1, that is,

$$R_s = 1 \text{ k}\Omega, R_1 = 40 \text{ k}\Omega, R_2 = 10 \text{ k}\Omega,$$

$$R_E = 2 \text{ k}\Omega, R_C = 4 \text{ k}\Omega, R_L = 2.2 \text{ k}\Omega$$

$$C_s = 10 \text{ mF}, C_c = 1 \text{ mF}, C_E = 20 \text{ mF}$$

$$h_{fe} = 100, r_o = \infty, V_{CC} = 20 \text{ V}$$

with the addition of  $C_{\pi}(C_{be}) = 36 \text{ pF}$ ,  $C_u(C_{bc}) = 4 \text{ pF}$ ,  $C_{ce} = 1 \text{ pF}$ ,  $C_{Wi} = 6 \text{ pF}$ ,

$$C_{Wo} = 8 \text{ pF}$$

a. Determine  $f_{Hi}$  and  $f_{Ho}$ .

a.

$$\beta r_e = 1.576 \text{ k}\Omega, \quad A_{v_{mid}}(\text{amplifier—not including effects of } R_s) = -90$$

$$\text{and} \quad R_{Th_i} = R_s \parallel R_1 \parallel R_2 \parallel \beta r_e = 1 \text{ k}\Omega \parallel 40 \text{ k}\Omega \parallel 10 \text{ k}\Omega \parallel 1.576 \text{ k}\Omega \\ \cong 0.57 \text{ k}\Omega$$

$$\text{with} \quad C_i = C_{Wi} + C_{be} + (1 - A_v)C_{bc} \\ = 6 \text{ pF} + 36 \text{ pF} + [1 - (-90)]4 \text{ pF} \\ = 406 \text{ pF}$$

$$f_{Hi} = \frac{1}{2\pi R_{Th_i} C_i} = \frac{1}{2\pi (0.57 \text{ k}\Omega)(406 \text{ pF})} \\ = 687.73 \text{ kHz}$$

$$R_{Th_o} = R_C \parallel R_L = 4 \text{ k}\Omega \parallel 2.2 \text{ k}\Omega = 1.419 \text{ k}\Omega$$

$$C_o = C_{Wo} + C_{ce} + C_{M_o} = 8 \text{ pF} + 1 \text{ pF} + \left(1 - \frac{1}{-90}\right)4 \text{ pF} \\ = 13.04 \text{ pF}$$

$$f_{Ho} = \frac{1}{2\pi R_{Th_o} C_o} = \frac{1}{2\pi (1.419 \text{ k}\Omega)(13.04 \text{ pF})} \\ = 8.6 \text{ MHz}$$



### 1.5. Low Frequency Response FET Amplifier

The analysis of the FET amplifier in the low-frequency region will be quite similar to that of the BJT amplifier. There are again three capacitors of primary concern as appearing in the network of Fig.15.  $C_G$ ,  $C_c$ , and  $C_s$ .

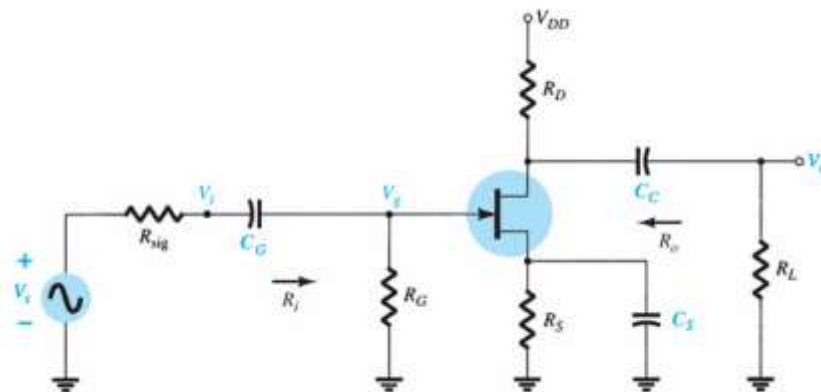


Fig.15. Capacitive elements that affect the low-frequency response of a JFET amplifier.

$C_G$  For the coupling capacitor between the source and the active device, the ac equivalent network is as shown in Fig. 16. The cutoff frequency determined by  $C_G$  is:

$$f_{LG} = \frac{1}{2\pi(R_{sig} + R_i)C_G}$$

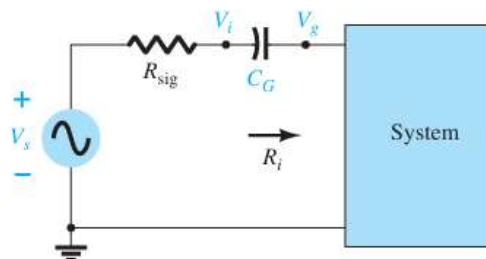


Fig.16. Determining the effect of  $C_G$  on the low-frequency response.



$$R_i = R_G$$

Typically,  $R_G \gg R_{sig}$ , and the lower cutoff frequency is determined primarily by  $R_G$  and  $C_G$ . The fact that  $R_G$  is so large permits a relatively low level of  $C_G$  while maintaining a low cutoff frequency level for  $f_{LG}$ .

$C_C$  For the coupling capacitor between the active device and the load the network of Fig.17.results. The resulting cutoff frequency is:

$$f_{Lc} = \frac{1}{2\pi(R_o + R_L)C_C}$$

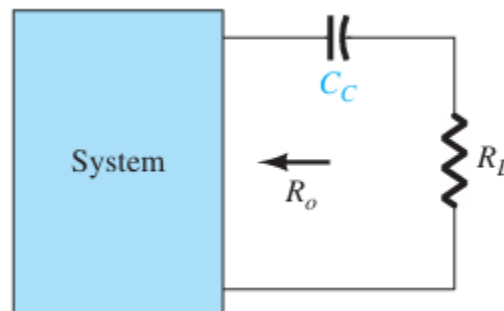


Fig.17. RL Determining the effect of  $C_C$  on the low-frequency response.

$C_S$  For the source capacitor  $C_S$ , the resistance level of importance. The cutoff frequency is defined by:

$$f_{Ls} = \frac{1}{2\pi R_{eq} C_S}$$





the resulting value of  $R_{eq}$  is

$$R_{eq} = \frac{R_S}{1 + R_S(1 + g_m r_d)/(r_d + R_D \parallel R_L)}$$

which for  $r_d \cong \infty \Omega$  becomes

$$R_{eq} = R_S \parallel \frac{1}{g_m} \quad r_d \cong \infty \Omega$$

### Example 4:

Determine the lower cutoff frequency for the network of Fig. 15 using the following parameters:

$$\begin{aligned} C_G &= 0.01 \mu\text{F}, \quad C_C = 0.5 \mu\text{F}, \quad C_S = 2 \mu\text{F} \\ R_{sig} &= 10 \text{ k}\Omega, \quad R_G = 1 \text{ M}\Omega, \quad R_D = 4.7 \text{ k}\Omega, \quad R_S = 1 \text{ k}\Omega, \quad R_L = 2.2 \text{ k}\Omega \\ I_{DSS} &= 8 \text{ mA}, \quad V_P = -4 \text{ V}, \quad r_d = \infty \Omega, \quad V_{DD} = 20 \text{ V} \end{aligned}$$

### Sol

DC analysis: Plotting the transfer curve of  $I_D = I_{DSS}(1 - V_{GS}/V_P)^2$  and superimposing the curve defined by  $V_{GS} = -I_D R_S$  results in an intersection at  $V_{GS_Q} = -2 \text{ V}$  and  $I_{D_Q} = 2 \text{ mA}$ . In addition,

$$g_{m0} = \frac{2I_{DSS}}{|V_P|} = \frac{2(8 \text{ mA})}{4 \text{ V}} = 4 \text{ mS}$$

$$g_m = g_{m0} \left( 1 - \frac{V_{GS_Q}}{V_P} \right) = 4 \text{ mS} \left( 1 - \frac{-2 \text{ V}}{-4 \text{ V}} \right) = 2 \text{ mS}$$

$$C_G \quad f_{L_G} = \frac{1}{2\pi(R_{sig} + R_i)C_G} = \frac{1}{2\pi(10 \text{ k}\Omega + 1 \text{ M}\Omega)(0.01 \mu\text{F})} \cong 15.8 \text{ Hz}$$

$$C_C \quad f_{L_C} = \frac{1}{2\pi(R_o + R_L)C_C} = \frac{1}{2\pi(4.7 \text{ k}\Omega + 2.2 \text{ k}\Omega)(0.5 \mu\text{F})} \cong 46.13 \text{ Hz}$$

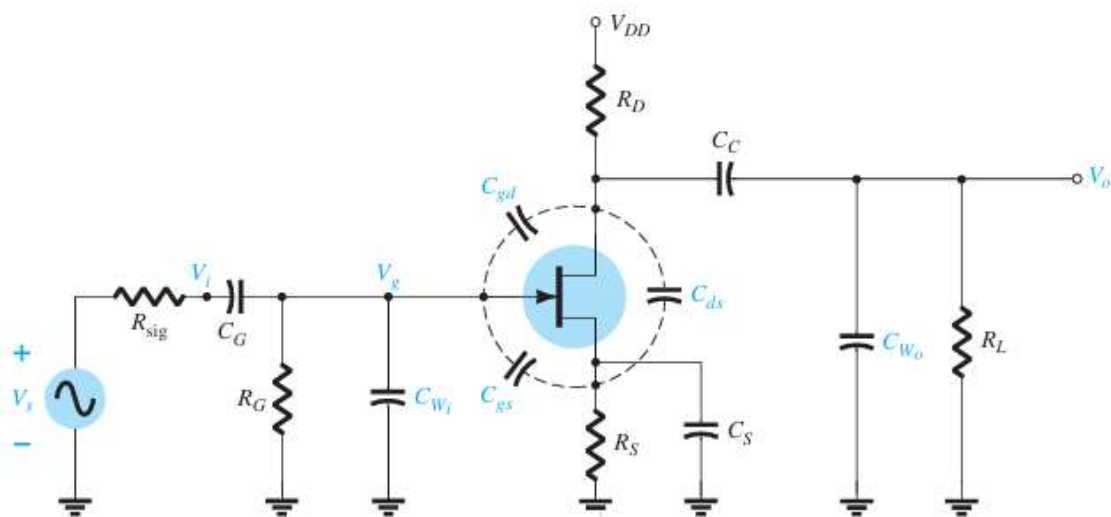
$$C_S \quad R_{eq} = R_S \parallel \frac{1}{g_m} = 1 \text{ k}\Omega \parallel \frac{1}{2 \text{ mS}} = 1 \text{ k}\Omega \parallel 0.5 \text{ k}\Omega = 333.33 \Omega$$

$$\text{Eq. (9.40): } f_{L_S} = \frac{1}{2\pi R_{eq} C_S} = \frac{1}{2\pi(333.33 \Omega)(2 \mu\text{F})} = 238.73 \text{ Hz}$$



### 1.5. High Frequency Response FET Amplifier

The analysis of the high-frequency response of the FET amplifier will proceed in a very similar manner to that encountered for the BJT amplifier. As shown in Fig. 18, there are interelectrode and wiring capacitances that will determine the high-frequency characteristics of the amplifier. The capacitors  $C_{gs}$  and  $C_{gd}$  typically vary from 1 pF to 10 pF, whereas the capacitance  $C_{ds}$  is usually quite a bit smaller, ranging from 0.1 pF to 1 pF.



Capacitive elements that affect the high-frequency response of a JFET amplifier.

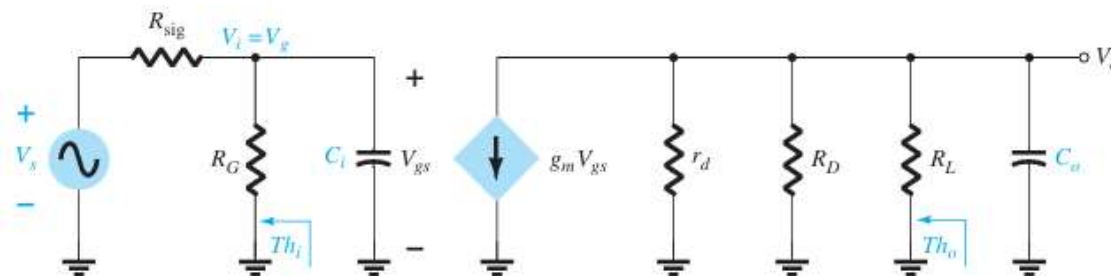
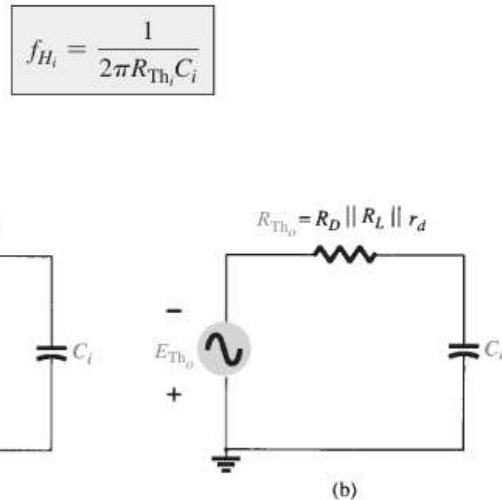


Fig.18. High-frequency ac equivalent circuit



The cutoff frequencies defined by the input and output circuits can be obtained by first finding the Thevenin equivalent circuits for each section as shown in Fig.

18. For the input circuit,



**Fig.18. The Thevenin equivalent circuits for: (a) the input circuit and (b) the output circuit.**

and

$$R_{Th_i} = R_{sig} \parallel R_G$$

with

$$C_i = C_{W_i} + C_{gs} + C_{M_i}$$

and

$$C_{M_i} = (1 - A_v)C_{gd}$$

for the output circuit,

$$f_{H_o} = \frac{1}{2\pi R_{Th_o} C_o}$$

with

$$R_{Th_o} = R_D \parallel R_L \parallel r_d$$

and

$$C_o = C_{W_o} + C_{ds} + C_{M_o}$$

and

$$C_{M_o} = \left(1 - \frac{1}{A_v}\right)C_{gd}$$



### Homework

Determine the high-cutoff frequencies for the network of Fig.18. using the same parameters as Example 4:

$$\begin{aligned}C_G &= 0.01 \mu\text{F}, & C_C &= 0.5 \mu\text{F}, & C_S &= 2 \mu\text{F} \\R_{\text{sig}} &= 10 \text{ k}\Omega, & R_G &= 1 \text{ M}\Omega, & R_D &= 4.7 \text{ k}\Omega, & R_S &= 1 \text{ k}\Omega, & R_L &= 2.2 \text{ k}\Omega \\I_{DSS} &= 8 \text{ mA}, & V_P &= -4 \text{ V}, & r_d &= \infty \Omega, & V_{DD} &= 20 \text{ V} \\&\text{with the addition of} \\C_{gd} &= 2 \text{ pF}, & C_{gs} &= 4 \text{ pF}, & C_{ds} &= 0.5 \text{ pF}, & C_{W_i} &= 5 \text{ pF}, & C_{W_o} &= 6 \text{ pF}\end{aligned}$$