

# Al-Mustaqbal University Department (Medical Instrumentation Techniques Engineering) Class (3<sup>rd</sup>)

Subject (Electrical Technology)
Lecturer (Dr. Osamah Jaber Ghayyib)

1sterm – Lect. (Induction machine types and equivalent circuit)

**Example2:** The following are the parameters of a 230V, 50 Hz, 4-pole, single phase induction motor  $R_1$ = 2.2 $\Omega$ ;  $X_1$ = 3.0  $\Omega$ ;  $R'_2$  = 3.8  $\Omega$ ;  $X'_2$  = 2.1  $\Omega$ ;  $X_m$  = 86  $\Omega$ 

Calculate the input current and power when the motor is operating at full-load speed of 1410 rpm. If the mechanical losses (iron and friction loss) are 60 W, determine gross power developed, useful power at the shaft, shaft torque and efficiency.

### **Solution**

Here, V = 230 V; f = 50 Hz; P = 4; N = 1410 rpm  

$$R_1$$
= 2.2  $\Omega$ ;  $X_1$ = 3.0  $\Omega$ ;  $R'_2$  = 3.8  $\Omega$ ;  $X'_2$  = 2.1  $\Omega$ ;  $X_m$  = 86  $\Omega$   
 $N_s = \frac{120 \ f}{R} = 1500 \text{ rpm}$ 

$$s = \frac{N_s - N}{N_s} = \frac{1500 - 1410}{1500} = 0.06$$

$$\frac{R_2'}{2S} = \frac{3.8}{2 \times 0.06} = 31.67 \ \Omega; \frac{X_2'}{2} = \frac{2.1}{2} = 1.05 \ \Omega$$

$$\frac{R_2'}{2(2-S)} = \frac{3.8}{2(2-0.06)} = 0.98 \ \Omega; \frac{X_m}{2} = \frac{86}{2} = 43 \ \Omega$$

$$Z_f = \frac{j\frac{X_m}{2}\left(\frac{R_2'}{2S} + j\frac{X_2'}{2}\right)}{\frac{R_2'}{2S} + j\left(\frac{X_m}{2} + \frac{X_2'}{2}\right)} = \frac{j43(31.67 + j1.05)}{31.67 + j(43 + 1.05)}$$

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$$= (25.22 \angle 37.61^{\circ}) \text{ ohm} = (19.98 + j 15.39) \Omega$$

$$Z_b = \frac{j \frac{X_m}{2} \left(\frac{R'_2}{2(2-S)} + j \frac{X'_2}{2}\right)}{\frac{R'_2}{2(2-S)} + j \left(\frac{X_m}{2} + \frac{X'_2}{2}\right)}$$

$$= \frac{j43(0.98 + j1.05)}{0.98 + j(43 + 1.05)}$$

$$= 1.40 \angle 48.3^{\circ} = (0.933 + j1.05) \Omega$$

Total impedance, 
$$Z_T = Z_1 + Z_f + Z_b$$
  

$$= (2.2 + j3) + (19.98 + j15.39) + (0.933 + j1.05)$$

$$= (23.11 + j19.44) \Omega = 30.2 \angle 40.1^{\circ}$$
Input current,  $I_I = \frac{V}{Z_T} = \frac{230 \angle 0^{\circ}}{30.2 \angle 40.1^{\circ}} = 7.616 \angle -40.1^{\circ} \text{ A}$ 

$$I_I = \textbf{7.616 A (Ans.)}$$
Input power,  $P = I_1^2 R_T = (7.616)^2 \times 23.11 = \textbf{1340 W (Ans.)}$ 

**Example3:** A 220V, four-pole, 50 Hz, single-phase induction motor has the following Parameters. R1 = 2.3  $\Omega$ , X1 = X2' = 3.2  $\Omega$ , R2' = 4.2  $\Omega$ , Xm = 74  $\Omega$ . Iron losses is given as 80W.

Windage and Friction loss is 20W. If this motor is running at 1425 rpm at rated voltage and frequency, determine the following

- (a) Stator current
- (b) Input Power factor
- (c) Power output
- (d) Output Torque



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# (e) Efficiency

Assuming auxiliary winding as open circuited.

### **Solution**

Synchronous speed 
$$N_S = \frac{120}{P} = \frac{120(50)}{4} = 1500 \text{rpm}$$

Slip is calculated as 
$$S = \frac{N_S - N}{N_S} = \frac{1500 - 142}{1500} = 0.05$$

Let us first calculate the impedance

Forward impedance

$$Z_f = \frac{j0.5X_m \left[ \frac{0.5R_2'}{s} + j0.5X_2' \right]}{\frac{0.5R_2'}{s} + j0.5X_2' + j0.5X_m} = 17.66 + j20.75\Omega$$

Backward impedance

$$Z_b = \frac{j0.5X_m \left[ \frac{0.5R_2'}{2-s} + j0.5X_2' \right]}{\frac{0.5R_2'}{2-s} + j0.5X_2' + j0.5X_m} = 0.99 + j1.562\Omega$$

Total impedance

$$Z = Z_f + Z_b = 20.95 + j25.5 = 33.1 \angle 50.4$$

(a) Stator current drawn by motor

$$I_1 = \frac{V_1}{Z} = \frac{220 \angle 0}{33.1 \angle 50.4} = 6.64 \angle -50.4$$

(b) Power Factor Cos(50.4) = 0.637 lagging

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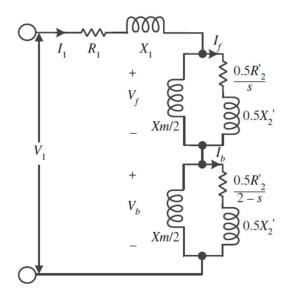
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(c) Power output is calculated by computing the total power input to the rotor side (air gap power)



 $P_{gf} =$  778.62 W  $P_{gb} =$  Mechanical

Air-gap power due to forward field 
$$(I_1)^2R_f=(6.64)^2(17.66)=$$
 Air-gap power due to backward field  $(I_1)^2R_b=(6.64)^2(0.99)=43.64~\mathrm{W}$  Power Developed by machine

$$P_m = (1 - s)(P_{gf} - P_{gb}) = (1 - 0.05)(778.62 - 43.64) = 698.22 \text{ W}$$

Output power = Mechanical power - Rotational Losses

Rotational Losses = Windage and Friction Losses + Iron Losses = 80 + 20 = 100 W

$$P_{\text{out}} = P_m - \text{R.Losses} = 698.22 - 100 = 598.22 \text{ W}$$

(d) Output Torque

Angular speed 
$$\omega_r = \frac{2\pi}{60} = \frac{2\pi(1425)}{60} = 149.22 \text{rad/s}$$

$$T_e = \frac{P_{\text{out}}}{\omega_r} = \frac{598.22}{149.22} = 4$$
Nm

(e) Efficiency is calculated as

Input power 
$$P_{in} = V_1 I_1 \cos(\theta) = 220(6.64)(0.637) = 930.53 \text{ W}$$

Efficiency 
$$\eta = \frac{P_{\rm out}}{P_{\rm in}} X 100\% = \frac{598.22}{930.53} \times 100\% = 64.3\%$$





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