



Subject Name: Numerical analysis

3rd Class, Second Semester

Academic Year: 2024-2025

Lecturer: Dr. Amir N.Saud

Email: amir-najah@uomus.edu.iq



Lecture No. 5

**Lecture Title: Least square fitting: the best-fitted line;
parabolic least square fitting) [Part 2)**

2. System of linear equations

- Many engineering and scientific problems require the solution of a system of linear equations.
- We consider a system of m linear equations in n unknowns written as,

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n &= b_1 \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots + a_{2n}x_n &= b_2 \\ a_{31}x_1 + a_{32}x_2 + a_{33}x_3 + \dots + a_{3n}x_n &= b_3 \\ &\dots \quad \dots \quad \dots \\ a_{m1}x_1 + a_{m2}x_2 + a_{m3}x_3 + \dots + a_{mn}x_n &= b_m \end{aligned}$$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \dots & a_{3n} \\ \dots & \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}, \quad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \dots \\ x_n \end{bmatrix}, \quad b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \dots \\ b_m \end{bmatrix}$$

- The solution of the non-homogeneous system exists, if the rank of the coefficient matrix A is equal to the rank of the augmented matrix [A : b] given by,

$$[A : b] = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} & b_2 \\ a_{31} & a_{32} & a_{33} & \dots & a_{3n} & b_3 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ a_{n1} & a_{n2} & a_{n3} & \dots & a_{nn} & b_n \end{bmatrix}$$

1. Classical Methods

Cramer's Rule: Let $D = |A|$ be the determinant of the coefficient matrix A and D_i be the determinant obtained by replacing the i^{th} column of D by the column vector b . The Cramer's rule gives the solution vector x by the equations,

$$x_i = \frac{D_i}{D} \text{ for } i = 1, 2, \dots, n$$

Example: Use Cramer's rule to solve the following system

$$\begin{bmatrix} 2 & -3 & 1 \\ 3 & 1 & -1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$D = \begin{vmatrix} 2 & -3 & 1 \\ 3 & 1 & -1 \\ 1 & -1 & -1 \end{vmatrix} = 2(-1-1) - 3(-1+3) + (-3-1) = -14$$

$$D_1 = \begin{vmatrix} 1 & -3 & 1 \\ 2 & 1 & -1 \\ 1 & -1 & -1 \end{vmatrix} = (-1-1) - 3(-1+2) + (-2-1) = -8$$

$$D_2 = \begin{vmatrix} 2 & 1 & 1 \\ 3 & 2 & -1 \\ 1 & 1 & -1 \end{vmatrix} = 2(-2+1) + (-1+3) + (3-2) = 1$$

$$D_3 = \begin{vmatrix} 2 & -3 & 1 \\ 3 & 1 & 2 \\ 1 & -1 & 1 \end{vmatrix} = 2(1+2) - 3(2-3) + (-3-1) = 5$$

Hence by Cramer's rule, we get

$$x_1 = \frac{D_1}{D} = \frac{-8}{-14} = \frac{4}{7}, \quad x_2 = \frac{D_2}{D} = \frac{-1}{14}, \quad x_3 = \frac{D_3}{D} = -\frac{5}{14}$$

2. Elimination Methods

Matrix Inversion Method

$$A^{-1} = \frac{\text{Adj } A}{|A|}$$

Where Adj A is the adjoint matrix obtained by transposing the matrix of the cofactors of the elements a_{ij} of the determinant of the coefficient matrix A.

$$\text{Adj } A = \begin{bmatrix} A_{11} & A_{21} \dots & A_{n1} \\ A_{12} & A_{22} \dots & A_{n2} \\ \dots & \dots & \dots \\ A_{1n} & A_{2n} \dots & A_{nn} \end{bmatrix}$$

A_{ij} being the cofactor of a_{ij} .

$$x = A^{-1}b$$

Example: Solve the given system of equations by matrix inversion method:

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 3 \\ 3 & 2 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix}$$

$$|A| = \begin{vmatrix} 1 & 1 & 1 \\ 2 & -1 & 3 \\ 3 & 2 & -1 \end{vmatrix} = 13 \quad \text{Adj } A = \begin{bmatrix} -5 & 3 & 4 \\ 11 & -4 & -1 \\ 7 & 1 & -3 \end{bmatrix} \quad A^{-1} = \frac{\text{Adj } A}{|A|} = \frac{1}{13} \begin{bmatrix} -5 & 3 & 4 \\ 11 & -4 & -1 \\ 7 & 1 & -3 \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = A^{-1}b = \frac{1}{13} \begin{bmatrix} -5 & 3 & 4 \\ 11 & -4 & -1 \\ 7 & 1 & -3 \end{bmatrix} \begin{bmatrix} 4 \\ 1 \\ 1 \end{bmatrix} = \frac{1}{13} \begin{bmatrix} -13 \\ 39 \\ 26 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \\ 2 \end{bmatrix}$$

Gaussian Elimination Method:

- This method consists in systematic elimination of the unknowns so as to reduce the coefficient matrix into an **upper triangular** system, which is then solved by the procedure of **back-substitution**.

Example: Solve the following system by Gauss elimination method:

$$\begin{array}{rcl} x_1 + 2x_2 + x_3 = 0 & \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 2 & 2 & 3 & 3 \\ -1 & -3 & 0 & 2 \end{array} \right] & \xrightarrow{-2R_1} \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & -2 & 1 & 3 \\ 0 & -1 & 1 & 2 \end{array} \right] \xrightarrow{-1/2R_2} \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & -2 & 1 & 3 \\ 0 & 0 & 1/2 & 1/2 \end{array} \right] \end{array}$$

$$x_1 = 1, x_2 = -1, x_3 = 1$$

Gauss-Jordan Elimination Method:

- The Gauss-Jordan elimination method is a variation of the Gaussian elimination method.
- In this method, the augmented coefficient matrix is transformed by row operations such that the coefficient matrix reduces to **the identity matrix**.

$$\left[\begin{array}{ccc|c} 2 & 2 & 4 & 18 \\ 1 & 3 & 2 & 13 \\ 3 & 1 & 3 & 14 \end{array} \right] \xrightarrow[R_1/2]{} \left[\begin{array}{ccc|c} 1 & 2 & 4 & 18 \\ 1 & 3 & 2 & 13 \\ 3 & 1 & 3 & 14 \end{array} \right] \xrightarrow[R_3 + 2R_2]{R_2 - R_1} \left[\begin{array}{ccc|c} 1 & 1 & 2 & 9 \\ 0 & 2 & 0 & 4 \\ 0 & -2 & -3 & -13 \end{array} \right]$$

$$\begin{bmatrix} 1 & 1 & 2 & : & 9 \\ 0 & 2 & 0 & : & 4 \\ 0 & -2 & -3 & : & -13 \end{bmatrix} \xrightarrow{R_2/2} \begin{bmatrix} 1 & 1 & 2 & : & 9 \\ 0 & 1 & 0 & : & 2 \\ 0 & -2 & -3 & : & -13 \end{bmatrix} \xrightarrow[\begin{smallmatrix} R_1 - R_2 \\ R_3 + 2R_2 \end{smallmatrix}]{\begin{smallmatrix} R_1 - R_2 \\ R_3 + 2R_2 \end{smallmatrix}} \begin{bmatrix} 1 & 0 & 2 & : & 7 \\ 0 & 1 & 0 & : & 2 \\ 0 & 0 & -3 & : & -9 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 2 & : & 7 \\ 0 & 1 & 0 & : & 2 \\ 0 & 0 & -3 & : & -9 \end{bmatrix} \xrightarrow{R_3/(-3)} \begin{bmatrix} 1 & 0 & 2 & : & 7 \\ 0 & 1 & 0 & : & 2 \\ 0 & 0 & 1 & : & 3 \end{bmatrix} \xrightarrow{R_1 - 2R_3} \begin{bmatrix} 1 & 0 & 0 & : & 1 \\ 0 & 1 & 0 & : & 2 \\ 0 & 0 & 1 & : & 3 \end{bmatrix}$$

$$x_1 = 1, x_2 = 2, x_3 = 3.$$